# Continuous Random Variables: Joint PDFs, Conditioning, Expectation and Independence 

Berlin Chen<br>Department of Computer Science \& Information Engineering<br>National Taiwan Normal University

## Reference:

- D. P. Bertsekas, J. N. Tsitsiklis, Introduction to Probability , Sections 3.4-3.6


## Multiple Continuous Random Variables (1/2)

- Two continuous random variables $X$ and $Y$ associated with a common experiment are jointly continuous and can be described in terms of a joint PDF $f_{X, Y}$ satisfying

$$
\mathbf{P}((X, Y) \in B)=\iiint_{(x, y) \in B} f_{X, Y}(x, y) d x d y
$$

- $f_{X, Y}$ is a nonnegative function
- Normalization Probability $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X, Y}(x, y) d x d y=1$
- Similarly, $f_{X, Y}(a, c)$ can be viewed as the "probability per unit area" in the vicinity of $(a, c)$

$$
\begin{aligned}
& \mathbf{P}(a \leq X \leq a+\delta, c \leq Y \leq c+\delta) \\
& =\int_{a}^{a+\delta} \int_{c}^{c+\delta} f_{X, Y}(x, y) d x d y=f_{X, Y}(a, c) \cdot \delta^{2}
\end{aligned}
$$

- Where $\delta$ is a small positive number


## Multiple Continuous Random Variables (2/2)

- Marginal Probability

$$
\begin{aligned}
\mathbf{P}(X \in A) & =\mathbf{P}(X \in A \text { and } X \in(-\infty,) \infty) \\
& =\int_{X \in A} \int_{-\infty}^{\infty} f_{X, Y}(x, y) d y d x
\end{aligned}
$$

- We have already defined that

$$
\mathbf{P}(X \in A)=\int_{X \in A} f_{X}(x) d x
$$

- We thus have the marginal PDF

$$
f_{X}(x)=\int_{-\infty}^{\infty} f_{X, Y}(x, y) d y
$$

Similarly

$$
f_{Y}(y)=\int_{-\infty}^{\infty} f_{X, Y}(x, y) d x
$$

## An Illustrative Example

- Example 3.10. Two-Dimensional Uniform PDF. We are told that the joint PDF of the random variables $X$ and $Y$ is a constant $c$ on an area $S$ and is zero outside. Find the value of $c$ and the marginal PDFs of $X$ and $Y$.

The correspond ing uniform joint PDF on an area $S$ is defined to be (cf. Example 3.9)

$$
\begin{aligned}
& f_{X, Y}(x, y)= \begin{cases}\frac{1}{\text { Size of area } S}, & \text { if }(x, y) \in S \\
0, & \text { otherwise }\end{cases} \\
& \Rightarrow f_{X, Y}(x, y)=\frac{1}{4} \text { for }(x, y) \in S
\end{aligned}
$$

$$
\begin{aligned}
& \text { for } 1 \leq x \leq 2 \\
& \Rightarrow f_{X}(x)=\int_{1}^{4} f_{X, Y}(x, y) d y \\
& \\
& =\int_{1}^{4} \frac{1}{4} d y=\frac{3}{4}
\end{aligned}
$$

$$
\text { for } \begin{aligned}
1 \leq y & \leq 2 \\
\Rightarrow f_{Y}(y) & =\int_{1}^{2} f_{X, Y}(x, y) d x \\
& =\int_{1}^{2} \frac{1}{4} d x=\frac{1}{4}
\end{aligned}
$$

$$
\text { for } \begin{aligned}
2 \leq x & \leq 3 \\
\Rightarrow f_{X}(x) & =\int_{2}^{3} f_{X, Y}(x, y) d y \\
& =\int_{2}^{3} \frac{1}{4} d y=\frac{1}{4}
\end{aligned}
$$




$$
\text { for } \begin{aligned}
3 \leq y & \leq 4 \\
\Rightarrow f_{Y}(y) & =\int_{1}^{2} f_{X, Y}(x, y) d x \\
& =\int_{1}^{2} \frac{1}{4} d x=\frac{1}{4}
\end{aligned}
$$

## Joint CDFs

- If $X$ and $Y$ are two (either continuous or discrete) random variables associated with the same experiment, their joint cumulative distribution function (Joint CDF) is defined by

$$
F_{X, Y}(x, y)=\mathbf{P}(X \leq x, Y \leq y)
$$

- If $X$ and $Y$ further have a joint PDF $f_{X, Y}(X$ and $Y$ are continuous random variables), then

$$
F_{X, Y}(x, y)=\int_{-\infty}^{x} \int_{-\infty}^{y} f_{X, Y}(s, t) d s d t
$$

$$
f_{X, Y}(x, y)=\frac{\partial^{2} F_{X, Y}(x, y)}{\partial x \partial y}
$$

If $F_{X, Y}$ can be differentiated at the point $(x, y)$

## An Illustrative Example

- Example 3.12. Verify that if $X$ and $Y$ are described by a uniform PDF on the unit square, then the joint CDF is given by

$$
F_{X, Y}(x, y)=\mathbf{P}(X \leq x, Y \leq y)=x y, \text { for } 0 \leq x, y \leq 1
$$



$$
\frac{\partial^{2} F_{X, Y}(x, y)}{\partial x \partial y}=1=f_{X, Y}(x, y), \text { for all }(x, y) \text { in the unit square }
$$

## Expectation of a Function of Random Variables

- If $X$ and $Y$ are jointly continuous random variables, and $g$ is some function, then $Z=g(X, Y)$ is also a random variable (can be continuous or discrete)
- The expectation of $Z$ can be calculated by

$$
\mathbf{E}[Z]=\mathbf{E}[g(X, Y)]=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f_{X, Y}(x, y) d x d y
$$

- If $Z$ is a linear function of $X$ and $Y$, e.g., $Z=a X+b Y$, then

$$
\mathbf{E}[Z]=\mathbf{E}[a X+b Y]=a \mathbf{E}[X]+b \mathbf{E}[Y]
$$

- Where $a$ and $b$ are scalars


## More than Two Random Variables

- The joint PDF of three random variables $X, Y$ and $Z$ is defined in analogy with the case of two random variables

$$
\mathbf{P}((X, Y, Z) \in B)=\iiint \int_{(X, Y, Z) \in B} f_{X, Y, Z}(x, y, z) d x d y d z
$$

- The corresponding marginal probabilities

$$
\begin{aligned}
& f_{X, Y}(x, y)=\int_{-\infty}^{\infty} f_{X, Y, Z}(x, y, z) d z \\
& f_{X}(x)=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X, Y, Z}(x, y, z) d y d z
\end{aligned}
$$

- The expected value rule takes the form

$$
\mathbf{E}[g(X, Y, Z)]=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y, z) f_{X, Y, Z}(x, y, z) d x d y d z
$$

- If $g$ is linear (of the form $a X+b Y+c Z$ ), then

$$
\mathbf{E}[a X+b Y+c Z]=a \mathbf{E}[X]+b \mathbf{E}[Y]+c \mathbf{E}[Z]
$$

## Conditioning PDF Given an Event (1/3)

- The conditional PDF of a continuous random variable $X$, given an event $A$
- If $A$ cannot be described in terms of $X$, the conditional PDF is defined as a nonnegative function $f_{X \mid A}(x)$ satisfying

$$
\mathbf{P}(X \in B \mid A)=\int_{B} f_{X \mid A}(x) d x
$$

- Normalization property

$$
\int_{-\infty}^{\infty} f_{X \mid A}(x) d x=1
$$

## Conditioning PDF Given an Event (2/3)

- If $A$ can be described in terms of $X(A$ is a subset of the real line with $\mathbf{P}(X \in A)>0)$, the conditional PDF is defined as a nonnegative function $f_{X \mid A}(x)$ satisfying

$$
f_{X \mid A}(x)= \begin{cases}\frac{f_{X}(x)}{\mathbf{P}(X \in A)}, & \text { if } x \in A \\ 0, & \text { otherwise }\end{cases}
$$

- The conditional PDF is zero outside the

$f_{X \mid A}$ remains the same shape as
$f_{X}$ except that it is scaled along the vertical axis

$$
\begin{aligned}
\mathbf{P}(X \in B \mid X \in A) & =\frac{\mathbf{P}(X \in B, X \in A)}{\mathbf{P}(X \in A)} \\
& =\frac{\int_{A \cap B} f_{X}(x) d x}{\mathbf{P}(X \in A)} \\
& =\int_{A \cap B} f_{X \mid A}(x) d x
\end{aligned}
$$

- Normalization Property $\int_{-\infty}^{\infty} f_{X \mid A}(x) d x=\int_{A} f_{X \mid A}(x) d x=1$


## Conditioning PDF Given an Event (3/3)

- If $A_{1}, A_{2}, \ldots, A_{n}$ are disjoint events with $\mathbf{P}\left(A_{i}\right)>0$ for each $i$, that form a partition of the sample space, then

$$
f_{X}(x)=\sum_{i=1}^{n} \mathbf{P}\left(A_{i}\right) f_{X \mid A_{i}}(x)
$$

- Verification of the above total probability theorem

```
think of {X\leqx} as an event B,
```

$$
\begin{aligned}
& \mathbf{P}(X \leq x)=\sum_{i=1}^{n} \mathbf{P}\left(A_{i}\right) \mathbf{P}\left(X \leq x \mid A_{i}\right) \quad \begin{array}{l}
\text { and use the total probability theorem } \\
\text { from Chapter 1 }
\end{array} \\
& \Rightarrow \int_{-\infty}^{x} f_{X}(t) d t=\sum_{i=1}^{n} \mathbf{P}\left(A_{i}\right) \int_{-\infty}^{x} f_{X \mid A_{i}}(t) d t
\end{aligned}
$$

Taking the derivative of both sides with respect to $x$

$$
\Rightarrow f_{X}(x)=\sum_{i=1}^{n} \mathbf{P}\left(A_{i}\right) f_{X \mid A_{i}}(x)
$$

## Illustrative Examples (1/2)

- Example 3.13. The exponential random variable is memoryless.
- The time $T$ until a new light bulb burns out is exponential distribution. John turns the light on, leave the room, and when he returns, $t$ time units later, find that the light bulb is still on, which corresponds to the event $A=\{T>t\}$
- Let $X$ be the additional time until the light bulb burns out. What is the conditional PDF of $X$ given A ?

$$
X=T-t, A=\{T>t\}
$$

$$
\begin{aligned}
& T \text { is exponential } \\
& f_{T}(t)=\left\{\begin{array}{l}
\lambda e^{-\lambda t}, t>0 \\
0,
\end{array}\right. \text { otherwise } \\
& P(T>t)=e^{-\lambda t}
\end{aligned}
$$

The conditional CDF of $X$ given $A$ is defined by
$P(X>x \mid A)=P(T-t>x \mid T>t)($ where $x \geq 0)$
$=P(T>t+x \mid T>t)=\frac{P(T>t+x \text { and } T>t)}{P(T>t)}$
$=\frac{P(T>t+x)}{P(T>t)}$
$=\frac{e^{-\lambda(t+x)}}{e^{-\lambda t}}$
$=e^{-\lambda x}$
$\therefore$ The conditiona 1 PDF of $X$ given the event $A$ is also exponential with parameter $\lambda$.

## Illustrative Examples (2/2)

- Example 3.14. The metro train arrives at the station near your home every quarter hour starting at 6:00 AM. You walk into the station every morning between $7: 10$ and $7: 30$ AM, with the time in this interval being a uniform random variable. What is the PDF of the time you have to wait for the first train to arrive?

- The arrival time, denoted by $X$, is a uniform random variable over the interval $7: 10$ to $7: 30$
-Let random varible $Y$ model the waiting time
- Let $A$ be a event
$A=\{7: 10 \leq X \leq 7: 15\}$ (You board the $7: 15$ train)
- Let $B$ be a event
$B=\{7: 15<X \leq 7: 30\}$ (You board the 7:30 train)
- Let $Y$ be uniform conditione d on $A$
- Let $Y$ be uniform conditione d on $B$

For $0 \leq y \leq 5, P_{Y}(y)=\frac{1}{4} \cdot \frac{1}{5}+\frac{3}{4} \cdot \frac{1}{15}=\frac{1}{10}$
For $5<y \leq 15, P_{Y}(y)=\frac{1}{4} \cdot 0+\frac{3}{4} \cdot \frac{1}{15}=\frac{1}{20}$

## Conditioning one Random Variable on Another

- Two continuous random variables $X$ and $Y$ have a joint PDF. For any $y$ with $f_{Y}(y)>0$, the conditional PDF of $X$ given that $Y=y$ is defined by

$$
f_{X \mid Y}(x \mid y)=\frac{f_{X, Y}(x, y)}{f_{Y}(y)}
$$

- Normalization Property $\int_{-\infty}^{\infty} f_{X \mid Y}(x \mid y) d x=1$
- The marginal, joint and conditional PDFs are related to each other by the following formulas

$$
\begin{aligned}
& f_{X, Y}(x, y)=f_{Y}(y) f_{X \mid Y}(x \mid y) \\
& f_{X}(x)=\int_{-\infty}^{\infty} f_{X, Y}(x, y) d y . \quad \text { marginalization }
\end{aligned}
$$

## Illustrative Examples (1/2)

- Notice that the conditional PDF $f_{X \mid Y}(x \mid y)$ has the same shape as the joint PDF $f_{X, Y}(x, y)$, because the normalizing factor $f_{Y}(y)$ does not depend on $x$


Figure 3.16: Visualization of the conditional PDF $f_{X \mid Y}(x \mid y)$.
Let $X, \quad Y$ have a joint PDF which is uniform on the set $S$. For each fixed $y$, we consider the joint PDF along the slice $Y=y$ and normalize it so that it integrates to 1

## Illustrative Examples (2/2)

- Example 3.15. Circular Uniform PDF. Ben throws a dart at a circular target of radius $r$. We assume that he always hits the target, and that all points of impact $(x, y)$ are equally likely, so that the joint PDF $f_{X, Y}(x, y)$ of the random variables $x$ and $y$ is uniform
- What is the marginal PDF $f_{Y}(y)$
$f_{X, Y}(x, y)= \begin{cases}\frac{1}{\text { area of the circle }}, & \text { if }(x, y) \text { is in the circle } \\ 0, & \text { otherwise }\end{cases}$

$$
= \begin{cases}\frac{1}{\pi r^{2}}, & x^{2}+y^{2} \leq r^{2} \\ 0, & \text { otherwise }\end{cases}
$$

$$
\begin{aligned}
f_{Y}(y) & =\int_{-\infty}^{\infty} f_{X, Y}(x, y) d x=\int_{x^{2}+y^{2} \leq r^{2}} \frac{1}{\pi r^{2}} d x \\
& =\frac{1}{\pi r^{2}} \int_{x^{2}+y^{2} \leq r^{2}} 1 d x=\frac{1}{\pi r^{2}} \int_{-\sqrt{r^{2}-y^{2}}}^{\sqrt{2}} 1 d x \\
& =\frac{2}{\pi r^{2}} \sqrt{r^{2}-y^{2}}, i f|y| \leq r
\end{aligned}
$$

(Notice here that $\operatorname{PDF} f_{Y}(y)$ is not uniform)


$$
=\frac{1}{2 \sqrt{r^{2}-y^{2}}}, \quad \text { if } x^{2}+y^{2} \leq r^{2}
$$

For each value $y, f_{X \mid Y}(x \mid y)$ is uniform

## Conditional Expectation Given an Event

- The conditional expectation of a continuous random variable $X$, given an event $A \quad(\mathbf{P}(A)>0)$, is defined by

$$
\mathbf{E}[X \mid A]=\int_{-\infty}^{\infty} x f_{X \mid A}(x) d x
$$

- The conditional expectation of a function $g(X)$ also has the form

$$
\mathbf{E}[g(X) \mid A]=\int_{-\infty}^{\infty} g(x) f_{X \mid A}(x) d x
$$

- Total Expectation Theorem
and

$$
\mathbf{E}[X]=\sum_{i=1}^{n} \mathbf{P}\left(A_{i}\right) \mathbf{E}\left[X \mid A_{i}\right]
$$

$$
\mathbf{E}[g(X)]=\sum_{i=1}^{n} \mathbf{P}\left(A_{i}\right) \mathbf{E}\left[g(X) \mid A_{i}\right]
$$

- Where $A_{1}, A_{2}, \ldots, A_{n}$ are disjoint events with $\mathbf{P}\left(A_{i}\right)>0$ for each $i$, that form a partition of the sample space


## An Illustrative Example

- Example 3.17. Mean and Variance of a Piecewise Constant PDF. Suppose that the random variable $X$ has the piecewise constant PDF

$$
f_{X}(x)= \begin{cases}1 / 3, & \text { if } 0 \leq x \leq 1 \\ 2 / 3, & \text { if } 1 \leq x \leq 2 \\ 0, & \text { otherwise }\end{cases}
$$

Define event $A_{1}=\{X$ lies in the first interval $[0,1]\}$ event $A_{2}=\{X$ lies in the second interval $[1,2]\}$
$\Rightarrow \mathbf{P}\left(A_{1}\right)=\int_{0}^{1} 1 / 3 d x=1 / 3, \mathbf{P}\left(A_{2}\right)=\int_{1}^{2} 2 / 3 d x=2 / 3$


$$
f_{X \mid A_{1}}(x)=\left\{\begin{array}{l}
\frac{f_{X}(x)}{P\left(X \in A_{1}\right)}=1, \quad 0 \leq x \leq 1 \\
0, \quad o_{X \mid A_{2}}(x)=\left\{\begin{array}{l}
\frac{f_{X}(x)}{P\left(X \in A_{2}\right)}=1, \quad 1 \leq x \leq 2 \\
0, \quad \text { otherwise }
\end{array} \quad . \quad f_{0} .\right.
\end{array}\right.
$$

| Recall that the mean and second moment of |
| :--- |
| a uniform random variable over an interval |
| $[a, b]$ is $(a+b) / 2$ and $\left(a^{2}+a b+b^{2}\right) / 3$ |

$$
\begin{aligned}
\Rightarrow & \mathrm{E}\left[X \mid A_{1}\right]=1 / 2, \mathrm{E}\left[X^{2} \mid A_{1}\right]=1 / 3 \\
& \mathrm{E}\left[X \mid A_{2}\right]=3 / 2, \mathrm{E}\left[X^{2} \mid A_{2}\right]=7 / 3
\end{aligned}
$$

Recall that the mean and second moment of a uniform random variable over an interval $[a, b]$ is $(a+b) / 2$ and $\left(a^{2}+a b+b^{2}\right) / 3$

## Conditional Expectation Given a Random Variable

- The properties of unconditional expectation carry though, with the obvious modifications, to conditional expectation

$$
\begin{aligned}
& \mathbf{E}[X \mid Y=y]=\int_{-\infty}^{\infty} x f_{X \mid Y}(x \mid y) d x \\
& \mathbf{E}[g(X) \mid Y=y]=\int_{-\infty}^{\infty} g(x) f_{X \mid Y}(x \mid y) d x \\
& \mathbf{E}[g(X, Y) \mid Y=y]=\int_{-\infty}^{\infty} g(x, y) f_{X \mid Y}(x \mid y) d x
\end{aligned}
$$

## Total Probability/Expectation Theorems

- Total Probability Theorem
- For any event $A$ and a continuous random variable $Y$

$$
\mathbf{P}(A)=\int_{-\infty}^{\infty} \mathbf{P}(A \mid Y=y) f_{Y}(y) d y
$$

- Total Expectation Theorem
- For any continuous random variables $X$ and $Y$

$$
\begin{aligned}
\mathbf{E}[X] & =\int_{-\infty}^{\infty} \mathbf{E}[X \mid Y=y] f_{Y}(y) d y \\
\mathbf{E}[g(X)] & =\int_{-\infty}^{\infty} \mathbf{E}[g(X) \mid Y=y] f_{Y}(y) d y \\
\mathbf{E}[g(X, Y)] & =\int_{-\infty}^{\infty} \mathbf{E}[g(X, Y) \mid Y=y] f_{Y}(y) d y
\end{aligned}
$$

## Independence

- Two continuous random variables $X$ and $Y$ are independent if

$$
f_{X, Y}(x, y)=f_{X}(x) f_{Y}(y), \text { for all } x, y
$$

- Since that

$$
f_{X, Y}(x, y)=f_{Y}(y) f_{X \mid Y}(x \mid y)=f_{X}(x) f_{Y \mid X}(y \mid x)
$$

- We therefore have

$$
f_{X \mid Y}(x \mid y)=f_{X}(x), \text { for all } x \text { and all } y \text { with } f_{Y}(y)>0
$$

- Or

$$
f_{Y \mid X}(y \mid x)=f_{Y}(y), \text { for all } y \text { and all } x \text { with } f_{X}(x)>0
$$

## More Factors about Independence (1/2)

- If two continuous random variables $X$ and $Y$ are independent, then
- Any two events of the forms $\{X \in A\}$ and $\{Y \in B\}$ are independent

$$
\begin{aligned}
\mathbf{P}(X \in A, Y \in B) & =\int_{x \in A} \int_{y \in B} f_{X, Y}(x, y) d y d x \\
& =\int_{x \in A} \int_{y \in B} f_{X}(x) f_{Y}(y) d y d x \\
& =\left[\int_{x \in A} f_{X}(x) d x\right]\left[\int_{y \in B} f_{Y}(y) d y\right] \\
& =\mathbf{P}(X \in A) \mathbf{P}(Y \in B)
\end{aligned}
$$

- It also implies that

$$
F_{X, Y}(x, y)=\mathbf{P}(X \leq x, Y \leq y)=\mathbf{P}(X \leq x) \mathbf{P}(Y \leq y)=F_{X}(x) F_{Y}(x)
$$

- The converse statement is also true (See the end-of-chapter problem 28)


## More Factors about Independence (2/2)

- If two continuous random variables $X$ and $Y$ are independent, then

$$
\begin{aligned}
& -\quad \mathbf{E}[X Y]=\mathbf{E}[X] \mathbf{E}[Y] \\
& -\quad \operatorname{var}(X+Y)=\operatorname{var}(X)+\operatorname{var}(Y)
\end{aligned}
$$

- The random variables $g(X)$ and $h(Y)$ are independent for any functions $g$ and $h$
- Therefore,

$$
\mathbf{E}[g(X) h(Y)]=\mathbf{E}[g(X)] \mathbf{E}[h(Y)]
$$

## Recall: the Discrete Bayes' Rule

- Let $A_{1}, A_{2}, \ldots, A_{n}$ be disjoint events that form a partition of the sample space, and assume that $\mathbf{P}\left(A_{i}\right) \geq 0$, for all $i$. Then, for any event $B$ such that $\mathbf{P}(B)>0$ we have

$$
\begin{aligned}
\mathbf{P}\left(A_{i} \mid B\right) & =\frac{\mathbf{P}\left(A_{i}\right) \mathbf{P}\left(B \mid A_{i}\right)}{\mathbf{P}(B)} \quad, \quad \text { Multiplic } \\
& =\frac{\mathbf{P}\left(A_{i}\right) \mathbf{P}\left(B \mid A_{i}\right)}{\sum_{k=1}^{n} \mathbf{P}\left(A_{k}\right) \mathbf{P}\left(B \mid A_{k}\right)} \\
& =\frac{\mathbf{P}\left(A_{i}\right) \mathbf{P}\left(B \mid A_{i}\right)}{\mathbf{P}\left(A_{1}\right) \mathbf{P}\left(B \mid A_{1}\right)+\cdots+\mathbf{P}\left(A_{n}\right) \mathbf{P}\left(B \mid A_{n}\right)}
\end{aligned}
$$

## Inference and the Continuous Bayes' Rule

- As we have a model of an underlying but unobserved phenomenon, represented by a random variable $X$ with PDF $f_{X}$, and we make a noisy measurement $Y$, which is modeled in terms of a conditional PDF $f_{Y \mid X}$. Once the experimental value of $Y$ is measured, what information does this provide on the unknown value of $X$ ?

$$
\begin{aligned}
& f_{X \mid Y}(x \mid y)=\frac{f_{X, Y}(x, y)}{f_{Y}(y)}=\frac{f_{X}(x) f_{Y \mid X}(y \mid x)}{\int_{-\infty}^{\infty} f_{X}(t) f_{Y \mid X}(y \mid t) d t}
\end{aligned}
$$

## Inference and the Continuous Bayes' Rule (2/2)

## Inference about a Discrete Random Variable

- If the unobserved phenomenon is inherently discrete
- Let $N$ is a discrete random variable of the form $\{N=n\}$ that represents the different discrete probabilities for the unobserved phenomenon of interest, and $p_{N}$ be the PMF of $N$

$$
\begin{aligned}
\mathbf{P}(N=n \mid Y=y) & \approx \mathbf{P}(N=n \mid y \leq Y \leq y+\delta) \\
& =\frac{\mathbf{P}(N=n) \mathbf{P}(y \leq Y \leq y+\delta \mid N=n)}{\mathbf{P}(y \leq Y \leq y+\delta)} \\
& \approx \frac{p_{N}(n) f_{Y \mid N}(y \mid n) \delta}{f_{Y}(y) \delta} \\
& =\frac{p_{N}(n) f_{Y \mid N}(y \mid n)}{\sum_{i} p_{N}(i) f_{Y \mid N}(y \mid i)}
\end{aligned}
$$

## Illustrative Examples (1/2)

- Example 3.19. A lightbulb produced by the General Illumination Company is known to have an exponentially distributed lifetime $Y$. However, the company has been experiencing quality control problems. On any given day, the parameter $\Lambda=\lambda$ of the PDF of $Y$ is actually a random variable, uniformly distributed in the interval [1,3/2].
- If we test a lightbulb and record its lifetime ( $Y=y$ ), what can we say about the underlying parameter $\lambda$ ?

$$
\begin{aligned}
& f_{Y \mid \Lambda}(y \mid \lambda)=\lambda e^{-\lambda y}, \quad y \geq 0, \lambda>0 \quad \begin{array}{l}
\text { Conditioned on } \Lambda=\lambda, Y \text { has a exponential distribution } \\
\text { with parameter } \lambda
\end{array} \\
& f_{\Lambda}(\lambda)= \begin{cases}2, & \text { for } 1 \leq \lambda \leq 3 / 2 \\
0, & \text { otherwise }\end{cases} \\
& f_{\Lambda \mid Y}(\lambda \mid y)=\frac{f_{\Lambda}(\lambda) f_{Y \mid \Lambda}(y \mid \lambda)}{\int_{1}^{3 / 2} f_{\Lambda}(t) f_{Y \mid \Lambda}(y \mid t) d t}=\frac{2 \lambda e^{-\lambda y}}{\int_{1}^{3 / 2} 2 t e^{-t y} d t}, \quad \text { for } 1 \leq \lambda \leq 3 / 2
\end{aligned}
$$

## Illustrative Examples (2/2)

- Example 3.20. Signal Detection. A binary signal $S$ is transmitted, and we are given that $\mathbf{P}(S=1)=p$ and $\mathbf{P}(S=-1)=1-p$.
- The received signal is $Y=S+N$, where $N$ normal noise with zero mean and unit variance , independent of $S$.
- What is the probability that $S=1$, as a function of the observed value $y$ of $Y$ ?

$$
f_{Y \mid S}(y \mid s)=\frac{1}{\sqrt{2 \pi} \sigma} e^{-(y-s)^{2} / 2} \text {, for } s=1 \text { and }-1 \text {, and }-\infty \leq y \leq \infty
$$

Conditioned on $S=s, Y$ has a normal distribution with mean $S$ and unit variance

$$
\begin{aligned}
\mathbf{P}(S=1 \mid Y=y) & =\frac{p_{S}(1) f_{Y \mid S}(y \mid 1)}{f_{Y}(y)}=\frac{p_{S}(1) f_{Y \mid S}(y \mid 1)}{p_{S}(1) f_{Y \mid S}(y \mid 1)+p_{S}(-1) f_{Y \mid S}(y \mid-1)} \\
& =\frac{p \frac{1 ;}{\sqrt{2 \pi}} e^{-(y-1)^{2} / 2}}{p \frac{1 ;}{\sqrt{2 \pi}} e^{-(y-1)^{2} / 2}+(1-p) \frac{1 ;}{\sqrt{2 \pi}} e^{-(y+1)^{2} / 2}} \\
& =\frac{e^{-\left(y^{\prime}+1\right) / 2} \cdot p e^{y}}{e^{-\left(y_{l}^{2},+1\right) / 2} \cdot p e^{y}+e^{-(y, i+1) / 2} \cdot(1-p) e^{-y}}=\frac{p e^{y}}{p e^{y}+(1-p) e^{-y}}
\end{aligned}
$$

## Inference Based on a Discrete Random Variable

- The earlier formula expressing $\mathbf{P}(A \mid Y=y)$ in terms of $f_{Y \mid A}(y)$ can be turned around to yield

$$
\begin{aligned}
f_{Y \mid A}(y) & =\frac{f_{Y}(y) \mathbf{P}(A \mid Y=y)}{\mathbf{P}(A)} \\
& =\frac{f_{Y}(y) \mathbf{P}(A \mid Y=y)}{\int_{-\infty}^{\infty} f_{Y}(t) \mathbf{P}(A \mid Y=t) d t}
\end{aligned}
$$

$$
\begin{aligned}
& \mathbf{P}(A) f_{Y \mid A}(y)=f_{Y}(y) \mathbf{P}(A \mid Y=y) \\
& \Rightarrow \int_{-\infty}^{\infty} \mathbf{P}(A) f_{Y \mid A}(y) d y=\int_{-\infty}^{\infty} f_{Y}(y) \mathbf{P}(A \mid Y=y) d y \\
& \Rightarrow \mathbf{P}(A)=\int_{-\infty}^{\infty} f_{Y}(y) \mathbf{P}(A \mid Y=y) d y\left(\because \text { normalizat ion property : } \int_{-\infty}^{\infty} f_{Y \mid A}(y) d y=1\right)
\end{aligned}
$$

## Recitation

- SECTION 3.4 Joint PDFs of Multiple Random Variables
- Problems 15, 16
- SECTION 3.5 Conditioning
- Problems 18, 20, 23, 24
- SECTION 3.6 The Continuous Bayes' Rule
- Problems 34, 35

